

1435. Measurement of stresses in polymeric films with Braille and tactile elements

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Abstract. The paper is devoted to the problem of stress measurements in polymeric films with Braille and tactile relief elements by using the method of photo-elasticity. A separate Braille and tactile relief element is analyzed numerically by using an axisymmetric model and the problem of determination of distribution of equivalent stress is investigated. Nodal stresses are calculated by using the procedure of conjugate approximation. Equivalent stresses are represented by intensity of the image. A special experimental setup was developed for the measurement of stresses in polymeric materials. The obtained results of investigations are used in the process of design of polymeric films with Braille and tactile relief elements by taking into account the stress distributions in them.

Keywords: Braille and tactile relief elements, polymeric film, axisymmetric problem, photo-elasticity.

1. Introduction

An important problem of the integration of disabled people (among them blind and visually impaired people) into the society exists in aging societies. Thus it becomes desirable to use the Braille and tactile relief elements on various products or their packages produced from polymeric and other materials [1-3].

Various stress distributions take place in transparent and usually optically isotropic polymeric materials. The character of distribution of stresses in these materials enables to measure the qualitative and quantitative parameters of Braille and tactile relief elements. Special requirements are to be satisfied in order to ensure sufficient quality of Braille and tactile relief elements during the process of use of a package or a label [4-6].

The main objective of this paper is to perform experimental stress analysis of the Polyethylene Terephthalate (PET) and Polypropylene (PP) polymers and their applicability for Braille and tactile relief elements. Also, this paper extends the investigations to new types of Braille and tactile relief elements. Braille and tactile relief elements are analyzed numerically by using an axisymmetric model and the distribution of equivalent stresses is investigated. Nodal stresses are calculated by using the procedure of conjugate approximation; equivalent stresses are represented by the grayscale level of the digital image. The numerical procedure is based on finite element analysis [7-9], the technique of conjugate approximation [7, 8] and representation of equivalent stresses [10].

A special experimental setup was developed for the measurement of distribution of stresses in samples of polymeric materials with Braille and tactile relief elements. Physical parameters of PET and PP samples are presented in Table 1 (these materials are used for packaging of food and non food type products) [3].

As mentioned previously, the main objective of this paper is to measure and investigate the character of distribution of stresses in polymeric packages with Braille and tactile relief elements and also in a special Braille and tactile relief element of axisymmetric type.

Table 1. Physical parameters of investigated samples [3]

Parameter	Samples	
	Plastic PET	Plastic PP
Modulus of elasticity, E (MPa)	1.41×10^4	1032-1720
Poissons ratio, ν	0.44	0.45
Strength in tension, (MPa)	172	29.3-38.6
Breaking elongation, (%)	12-55	100-600
Impact strength, (MPa)	13-35	2.8-6.9
Thickness of the material, (mm)	0.25	1.0
Density of the material, (g/cm ³)	1.335	0.85-0.854

2. Investigation of stress distributions in axisymmetric Braille elements

2.1. The description of the numerical procedure

Nodal values of the stresses are determined from:

$$[\hat{K}][\{\delta_x\} \ \{\delta_y\} \ \{\delta_z\} \ \{\delta_{xy}\}] = [\hat{F}], \quad (1)$$

where x stands for the radial coordinate; y denotes the axial coordinate; z denotes the coordinate in the angular direction; $\{\delta_x\}$, $\{\delta_y\}$, $\{\delta_z\}$, $\{\delta_{xy}\}$ are the vectors of nodal values of the stresses σ_x , σ_y , σ_z , τ_{xy} and:

$$[\hat{K}] = \int [\hat{N}]^T [\hat{N}] 2\pi x dx dy, \quad (2)$$

$$[\hat{F}] = \int [\hat{N}]^T [\sigma_x \ \sigma_y \ \sigma_z \ \tau_{xy}] 2\pi x dx dy, \quad (3)$$

where $[\hat{N}]$ is the row of the shape functions N_1, N_2, \dots, N_9 of the two dimensional Lagrange quadratic finite element.

Stresses in the expression of $[\hat{F}]$ are determined from:

$$\begin{pmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \end{pmatrix} = [D][B]\{\delta\}, \quad (4)$$

where $\{\delta\}$ is the vector of nodal displacements, $[D]$ is the matrix of elastic constants and:

$$[B] = \begin{bmatrix} \frac{\partial N_1}{\partial x} & 0 & \dots \\ 0 & \frac{\partial N_1}{\partial y} & \dots \\ \frac{N_1}{x} & 0 & \dots \\ \frac{\partial N_1}{\partial y} & \frac{\partial N_1}{\partial x} & \dots \end{bmatrix}. \quad (5)$$

2.2. Braille element of type I: the stress field for a quarter of a disk

The structure consists of one row of elements located on one fourth of a disk with radius of the middle line 0.001 m and semi thickness 0.0001 m. The following parameters are assumed:

modulus of elasticity $E = 10.32 \times 10^8$ Pa, Poisson's ratio $\nu = 0.45$, density of the material $\rho = 850$ kg/m³. The left end of the structure coincides with the axis of symmetry. 64 two dimensional Lagrange quadratic finite elements are used; the finite element mesh is illustrated in Fig. 1.

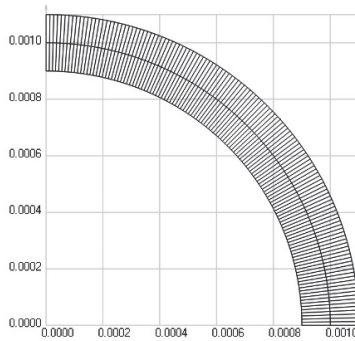


Fig. 1. Finite element mesh of the structure

2.2.1. The static problem

Displacements in the direction of the x axis of the three nodes on the left end of the structure and displacements in the direction of the y axis of the three nodes on the right end of the structure are assumed equal to zero. Non-dimensional displacements in the direction of the x axis of the three nodes on the right end of the structure are assumed equal to one (the structure has 765 degrees of freedom after taking the boundary conditions into account). Equivalent stresses are represented by grayscale levels in Fig. 2 (black color of the images corresponds to highest values of equivalent stress; white color corresponds to lowest values of equivalent stress); the grayscale bar is presented in Fig. 3.



Fig. 2. Equivalent stresses

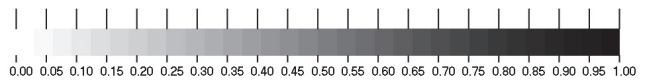


Fig. 3. The grayscale bar

2.2.2. Visualization of the eigenmodes

Displacements in the direction of the x axis of the three nodes on the left end and all displacements of the three nodes on the right end of the structure are assumed equal to zero. Equivalent stresses for the first ten eigenmodes are presented in Fig. 4.

It is clear that the complexity of stress distribution in general increases with the increase of the number of the eigenmode and that maximum values of equivalent stress are usually located at the surface of the structure. But experimental investigations of polymeric materials with Braille elements of this type indicate that polymeric Braille materials of this type experience degradation of strength at their top parts due to frequent contacts with fingers. Thus Braille elements having a flat top part are to be preferred what leads to the investigation of Braille elements of the second type.

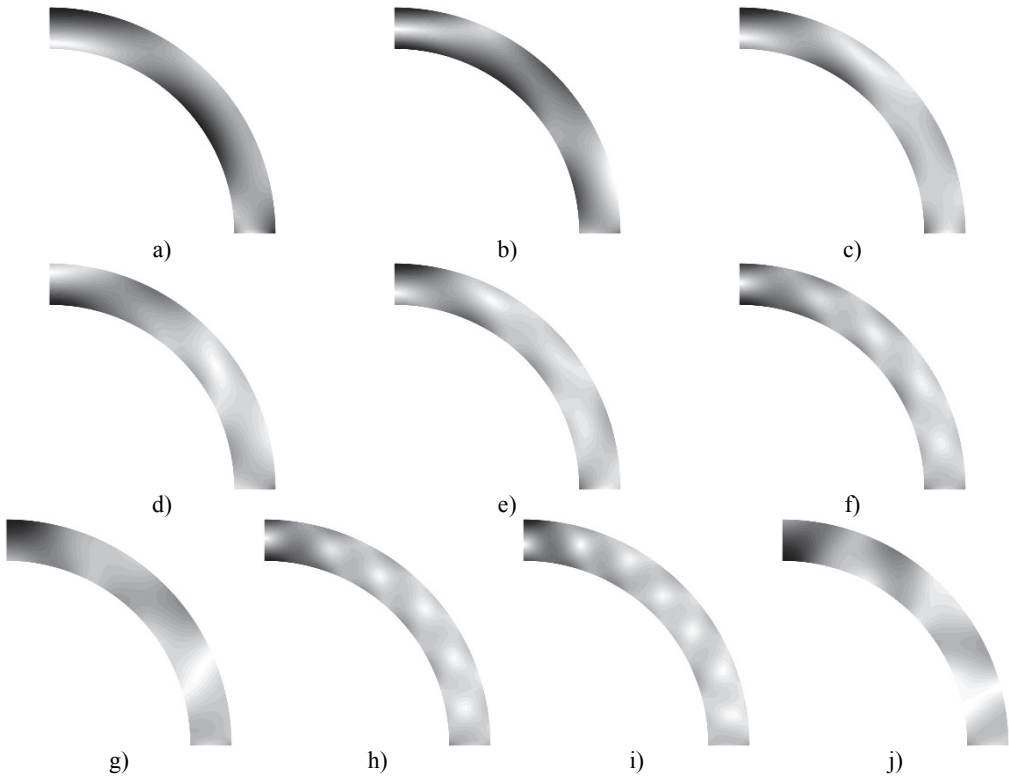


Fig. 4. Equivalent stresses for a) the first, b) the second, ..., j) the tenth eigenmodes

2.3. Braille element of type II: the stress field for the structure with improved tactile relief element

The structure consists of one row of elements located on a straight part with the length equal to the length of the middle line of one fourth of a circle with another part comprising a quarter of the disk. The radius of the middle line of the part of the circle is 0.001 m and semi thickness of the structure is 0.0001 m. The following parameters are assumed: modulus of elasticity $E = 10.32 \times 10^8$ Pa, Poisson's ratio $\nu = 0.45$, density of the material $\rho = 850$ kg/m³. The left end of the structure coincides with the axis of symmetry; 64 2D Lagrange quadratic finite elements are used: 32 for the straight part and 32 for the circular part.

2.3.1. The static problem

Displacements in the direction of the x axis of the three nodes on the left end of the structure and displacements in the direction of the y axis of the three nodes on the right end of the structure are assumed equal to zero. Non-displacements in the direction of the x axis of the three nodes on the right end of the structure are assumed equal to one (after taking the boundary conditions into account the structure comprises 765 degrees of freedom) Equivalent stresses are presented in Fig. 5.



Fig. 5. Equivalent stresses

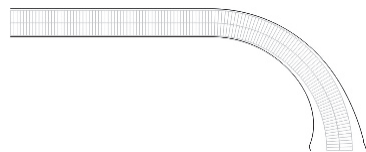


Fig. 6. Equivalent stresses on the lower and upper surfaces

As noted previously, Braille elements with a flat top part have an advantage over the Braille elements of the first type. Thus they are recommended for practical applications and deserve more detailed analysis. Maximum equivalent stress usually takes place at the surfaces of the Braille and tactile relief element. In order to be able to interpret the values of equivalent stress on the lower and upper surfaces of the Braille element a graphical representation is desirable. Equivalent stresses on the lower and upper surfaces represented in the normal direction to the surfaces are presented in Fig. 6.

Displacements in the direction of the x axis of the three nodes on the left end of the structure and all displacements of the three nodes on the right end of the structure are assumed equal to zero (after taking the boundary conditions into account the structure has 765 degrees of freedom) Equivalent stresses for the first ten eigenmodes are presented in Fig. 7. Equivalent stresses on the lower and upper surfaces represented in the normal direction to the surfaces are presented in Fig. 8.

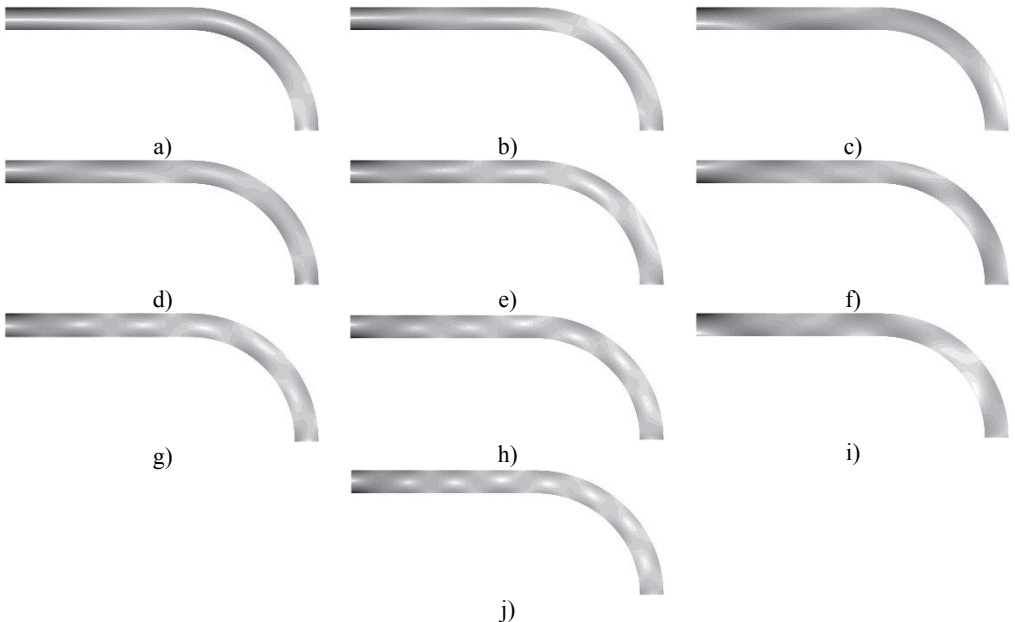


Fig. 7. Equivalent stresses for a) the first, b) the second, ..., j) the tenth eigenmodes

3. Experimental measurements of stresses in a sheet of polymeric film with Braille elements

3.1. The experimental setup

A special experimental setup was produced for the investigation of distributions of stresses in polymeric packages with Braille and tactile relief elements. It comprises General Purpose Strain Viewer produced by the company Sharpless, digital camera EO-1312c and a personal computer (Fig. 9).

Geometrical parameters of Braille and tactile relief elements are presented in Fig. 10. Two different samples of transparent polymeric materials were investigated: PET samples with formed surface elements (sample 1 and sample 2) and PP samples with elements of Braille writings (sample 3). Measurement of distribution of stresses in the investigated samples are performed in static conditions.

Transparent optically isotropic polymeric material becomes optically anisotropic during the process of production due to residual stresses. Thus it divides the propagating light into two polarized waves which occur due to different velocities of the propagation of waves in the polymeric material in different directions. This reason causes a time delay when mutually

perpendicular polarized waves reach the observer. The image produced by the polariscope represents this time delay – in the regions of polymeric material with stresses result in white areas, while the unstressed regions result into dark areas.

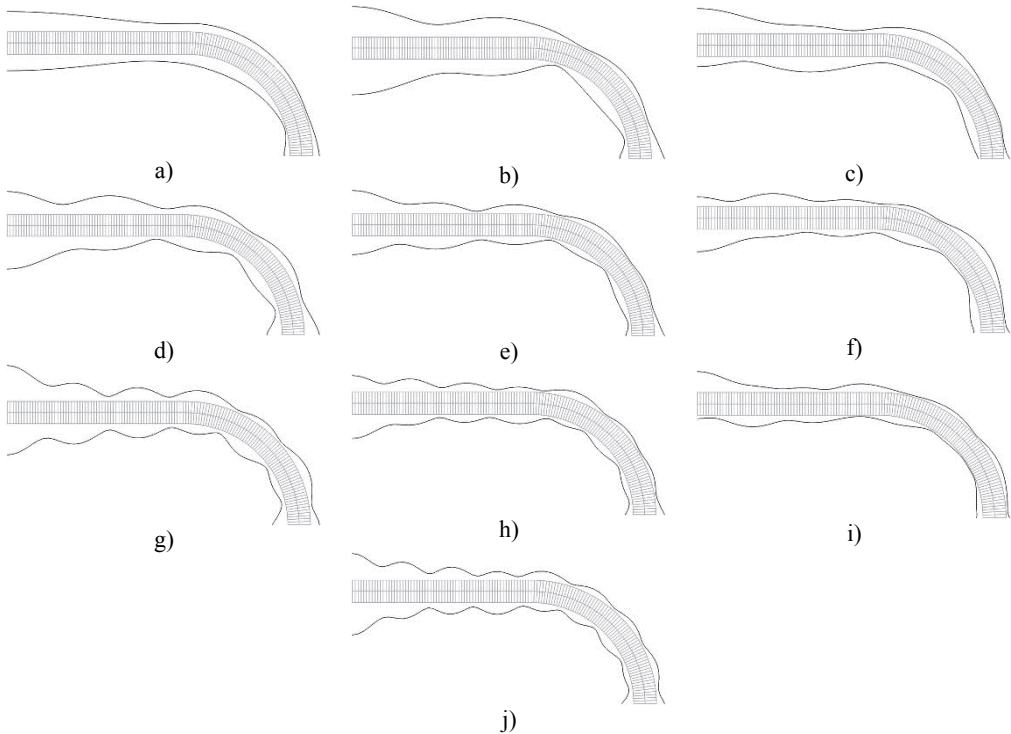


Fig. 8. Equivalent stresses on the lower and upper surfaces for
 a) the first, b) the second, ..., j) the tenth eigenmodes

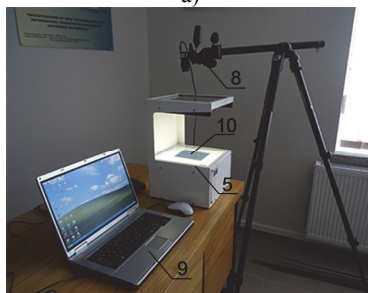
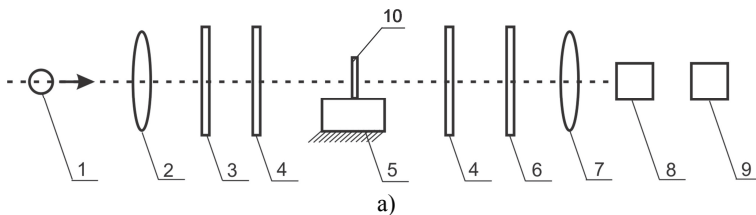


Fig. 9. Layout of the setup for investigation of stresses: a) structural diagram; b) external view of the designed experimental setup: 1 – stands for the light source, 2 – collimating lens, 3 – polarizer, 4 – quarter wave plate, 5 – background on which a sample is located, 6 – analyzer, 7 – field lens, 8 – digital camera EO-1312c, 9 – personal computer, 10 – investigated sample

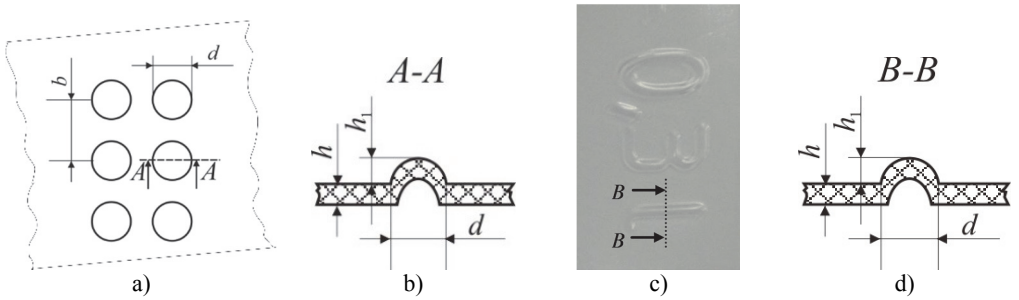


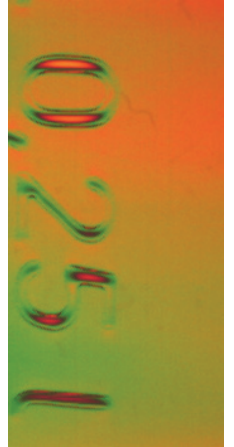
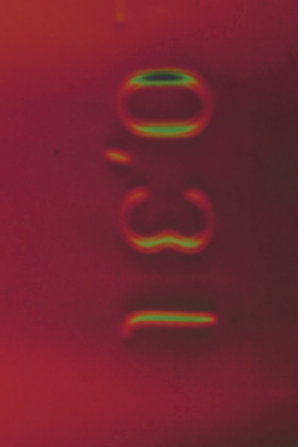
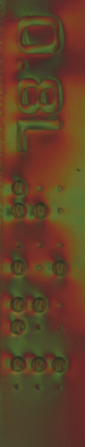
Fig. 10. Representation of geometric parameters of Braille and tactile relief elements: a) top view of the Braille element: d – diameter of the Braille dot, b – distance between Braille dots; b) side view of Braille on polymeric material ($A-A$): h – thickness of polymeric material, h_1 – height of the Braille dot; c) the surface of the graphical image; d) profiles of surface elements ($B-B$): h – thickness of the polymeric material, h_1 – height of the graphical element, d – width of the graphical element

3.2. Results of experimental investigations

The images of samples obtained by using the method of photo-elasticity are presented in Table 2. The resulting interference color (see Table 3) enables optical determination of the time delay caused by the light wave propagation through the investigated sample.

Note that the color structure in samples 1, 2, 3 is similar; color regions of the fourth order dominate and the values of stresses are highest there. Stresses in the regions of Braille and tactile relief elements stresses can be clearly seen.

Table 2. Photo-elastic images for the samples

Sample 1	Sample 2	Sample 3
		

4. Conclusions

Separate Braille and tactile relief elements are investigated using computational techniques in an axisymmetric model geometry. Nodal stresses are calculated by using the procedure of conjugate approximation. Equivalent stresses are represented according to the intensity of the image. Two types of Braille and tactile relief elements were investigated: a quarter of a disk and a structure with the special type of tactile relief elements.

Results of experimental investigations indicate that Braille elements of the first type experience wear and degradation of strength of material at the top due to frequent contacts with fingers and other sheets of polymeric material. Thus Braille and tactile relief elements with a flat top could be considered as an alternative. Braille and tactile relief elements of the second type

have a flat top and thus are advantageous from the point of view of wear and degradation of strength of the polymeric material.

Table 3. Color index representing the source of white light [11]

Color	Nanometers (10 ⁻⁹ m)	Color	Nanometers (10 ⁻⁹ m)
First order colors		Second order colors	
Black	0	Green – yellow	830
Grey	140	Orange	960
White	260	Rose Red	1050
Pale yellow	330	Purple	1150
Orange	460	Green	1350
Dull red	520	Third order colors	
Purple	580	Green – yellow	1450
Deep blue	620	Pink	1550
Blue – green	700	Green	1800
		Fourth order colors	
		Pink	2100
		Green	2400

The darkest parts of the images correspond to highest values of equivalent stress. At those places the wear of material is highest. In general, higher eigenmodes correspond to more complicated distributions of equivalent stress and the highest equivalent stress is located at the surfaces of the tactile relief elements.

Braille elements of the second type have advantages in practical applications and are investigated in more details – graphical representations of the equivalent stress on the lower and upper surfaces are obtained. Such graphical representations help to determine places with the highest values of the equivalent stress.

An experimental setup based on photo-elastic method for the measurements of stresses in sheets of polymeric material with Braille and tactile relief elements is developed. The fourth order color structure is employed for the measurement of stresses in Braille elements. The obtained results are used for improvement of design of sheets of polymeric material, as well as packages, labels and pictures with Braille and tactile relief elements.

I. Venytė performed experimental measurements of stresses in a sheet of polymeric film with Braille elements. She also took part in the development of the numerical model of Braille and also in the development of the experimental setup. E. Kibirškis proposed and developed the experimental setup, performed the interpretation of experimental results and took part in the development of the numerical model. A. Voloshin enhanced the developed experimental setup used for investigations, investigated the correspondence between experimental and numerical results and took part in the interpretation of experimental results. K. Ragulskis proposed the geometries of Braille and tactile relief elements which were used in numerical calculations and performed the interpretation of the obtained numerical results. L. Ragulskis was responsible for the numerical implementation of the model.

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